

# SciTinyML

Scientific Use of Machine Learning on Low Power Devices

## Regional Workshop - Africa

### Hands-on Lab with Edge Impulse Motion Classification



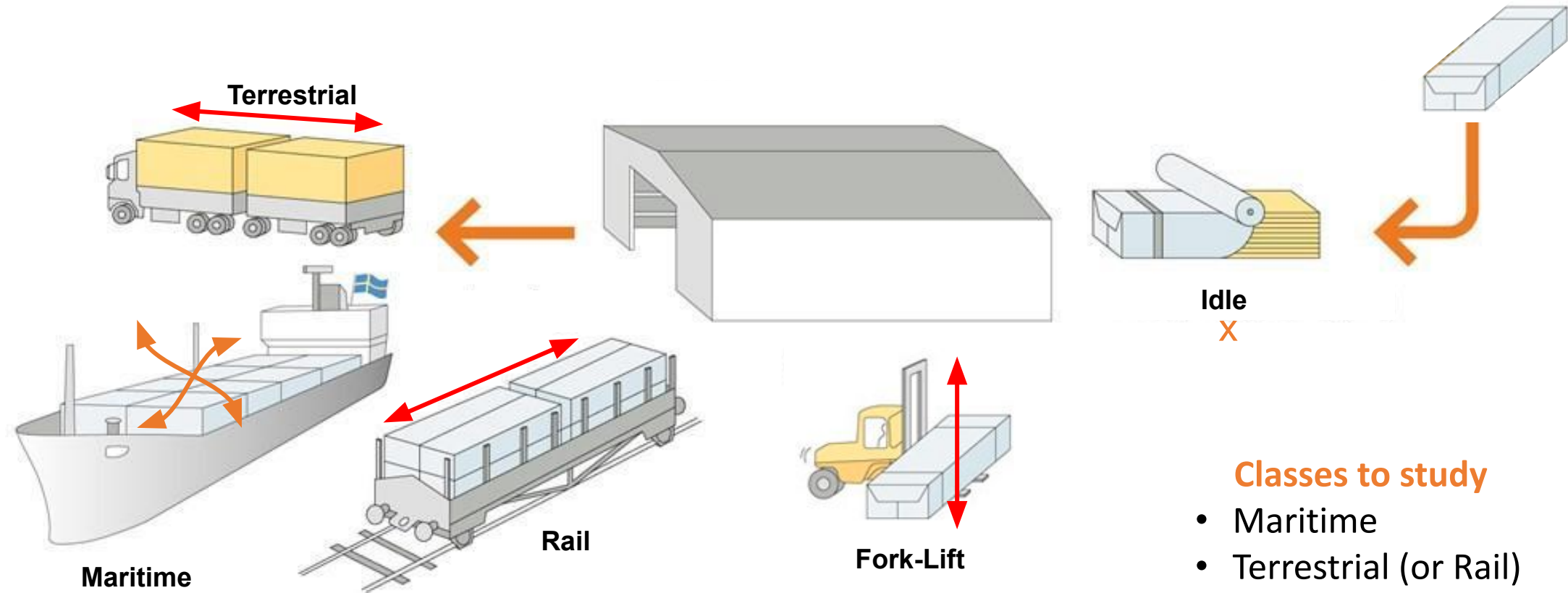
*Marcelo Rovai*  
Professor, UNIFEI - Brazil

*Shawn Himel*  
Senior DevRel Engineer, Edge Impulse



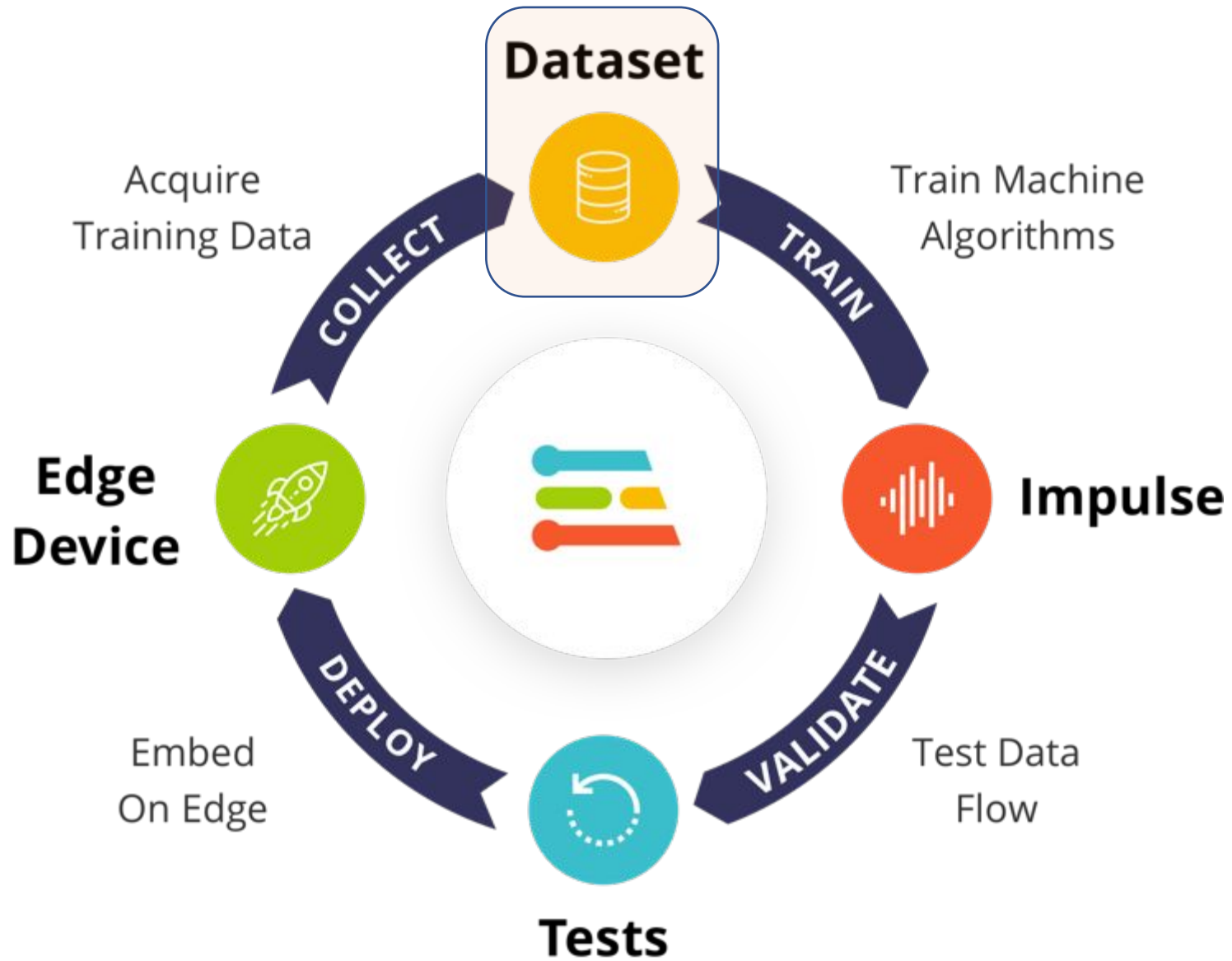
# Hands-on lab for motion classification

# Case Study: Mechanical Stresses in Transport



## Classes to study

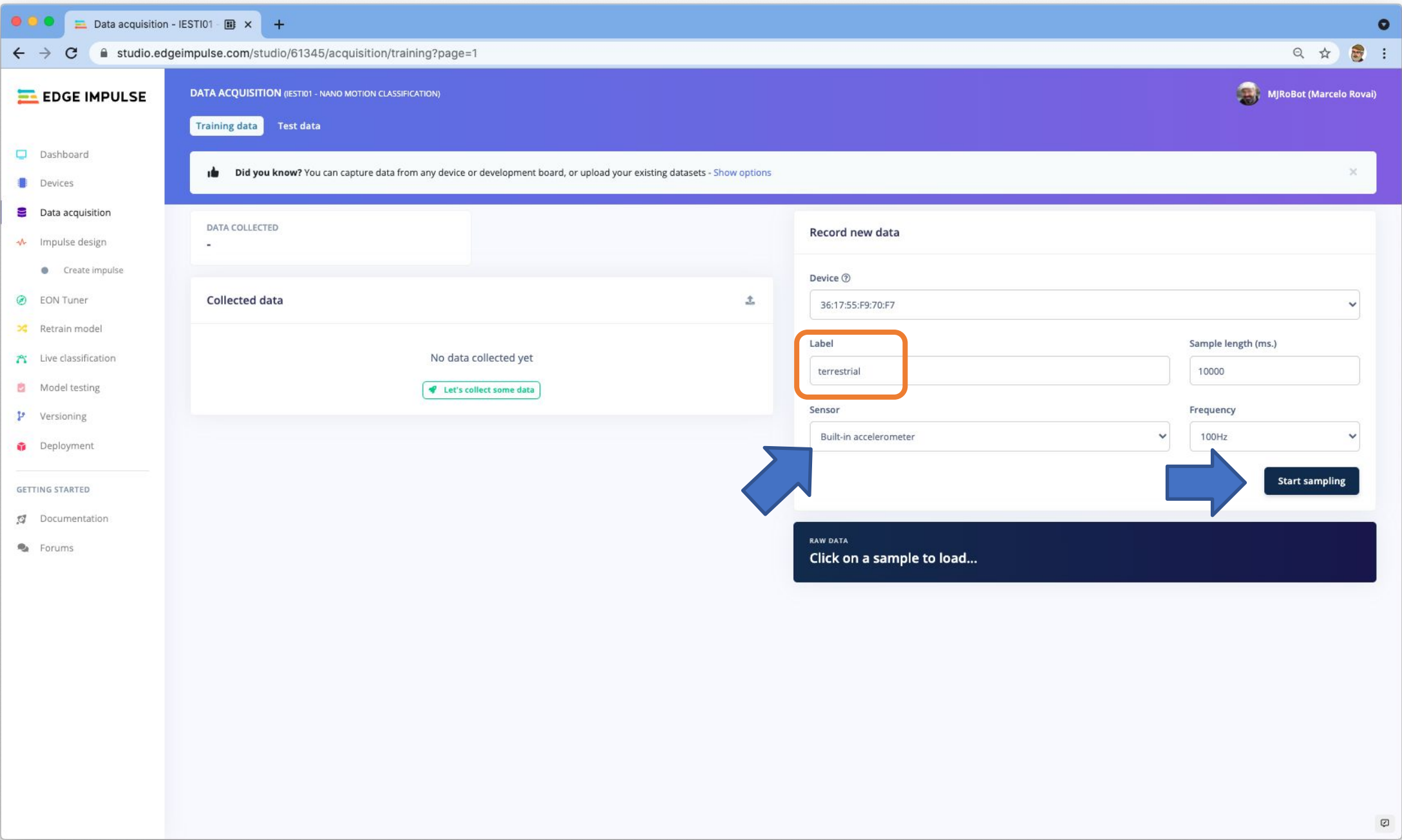
- Maritime
- Terrestrial (or Rail)
- Lift
- Idle



- Pre-Processing Data
- Design a Model
- Train a Model

The image shows a browser window with the URL `studio.edgeimpulse.com/studio/61345/acquisition/training?page=1`. A modal dialog is open, titled "studio.edgeimpulse.com wants to connect to a serial port". The dialog lists several serial ports, with "Nano 33 BLE (cu.usbmodem145101)" selected and highlighted in blue. A blue arrow labeled "2" points to this selection. Below the list are "Cancel" and "Connect" buttons, with a blue arrow labeled "3" pointing to the "Connect" button. In the background, the main interface has a "Record new data" section with a "Connect using WebUSB" button, which is circled in orange and labeled with a blue arrow and the number "1". The user's profile "MJRoBot (Marcelo Rovai)" is visible in the top right corner.

WebUSB works fine with Chrome



Did you know? You can capture data from any device or development board, or upload your existing datasets - Show options

DATA COLLECTED  
-

Collected data  
No data collected yet  
Let's collect some data

Record new data  
Device: 36:17:55:F9:70:F7  
Label: terrestrial  
Sample length (ms.): 10000  
Sensor: Built-in accelerometer  
Frequency: 100Hz  
Start sampling

RAW DATA  
Click on a sample to load...

Devices - IEST101 - Nano Moti... +

studio.edgeimpulse.com/studio/61345/devices

EDGE IMPULSE


DEVICES (IEST101 - NANO MOTION CLASSIFICATION)

MJRoBot (Marcelo Rovai)

### Your devices

[+ Connect a new device](#)

These are devices that are connected to the Edge Impulse remote management API, or have posted data to the ingestion SDK.

| NAME  | ID                | TYPE              | SENSORS                                     | REMOTE M...                          | LAST SEEN       |
|---|-------------------|-------------------|---|--------------------------------------|-----------------|
|  36:17:55:F9:70:F7 | 36:17:55:F9:70:F7 | ARDUINO_NANO33BLE | Built-in accelerometer, Built-in microph... | <span style="color: green;">●</span> | Today, 12:26:49 |

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- Dashboard
- Devices
- Data acquisition
- Impulse design
  - Create impulse
- EON Tuner
- Retrain model
- Live classification
- Model testing
- Versioning
- Deployment

GETTING STARTED

- Documentation
- Forums

EDGE IMPULSE

DATA ACQUISITION (IESTI01 - NANO MOTION CLASSIFICATION)

MJRoBot (Marcelo Rovai)

Training data | Test data

**Did you know?** You can capture data from any device or development board, or upload your existing datasets - [Show options](#)

DATA COLLECTED: 10s

TRAIN / TEST SPLIT: 100% / 0%

Collected data

| SAMPLE NAME               | LABEL       | ADDED           | LENGTH |
|---------------------------|-------------|-----------------|--------|
| terrestrial.json.2jvbimlk | terrestrial | Today, 13:01:46 | 10s    |

Record new data

Connect using WebUSB

Device: Nano

Label: terrestrial

Sample length (ms.): 10000

Sensor: Sensor with 3 axes (accX, accY, accZ)

Frequency: 100Hz

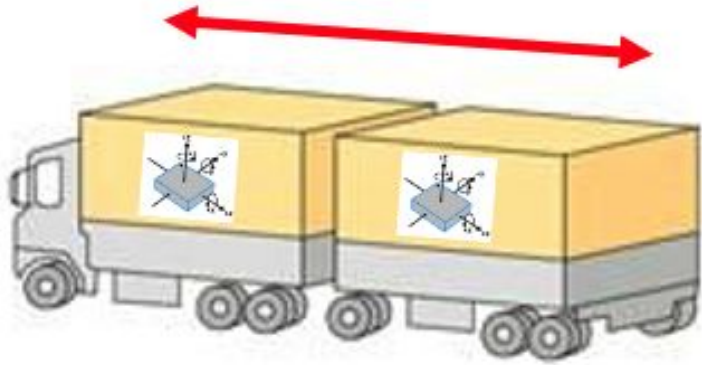
Start sampling

RAW DATA: terrestrial.json.2jvbimlk

accX accY accZ



# Label: terrestrial



The screenshot shows the Edge Impulse web interface for a project named "DATA ACQUISITION (IESTI01 - NANO MOTION CLASSIFICATION)". The interface includes a sidebar with navigation options like Dashboard, Devices, Data acquisition, Impulse design, EON Tuner, Retrain model, Live classification, Model testing, Versioning, and Deployment. The main content area displays training and test data statistics, a table of collected data, and configuration options for recording new data.

**DATA ACQUISITION (IESTI01 - NANO MOTION CLASSIFICATION)**

Training data | Test data

Did you know? You can capture data from any device or development board, or upload your existing datasets - Show options

DATA COLLECTED: 1m 40s | TRAIN / TEST SPLIT: 100% / 0%

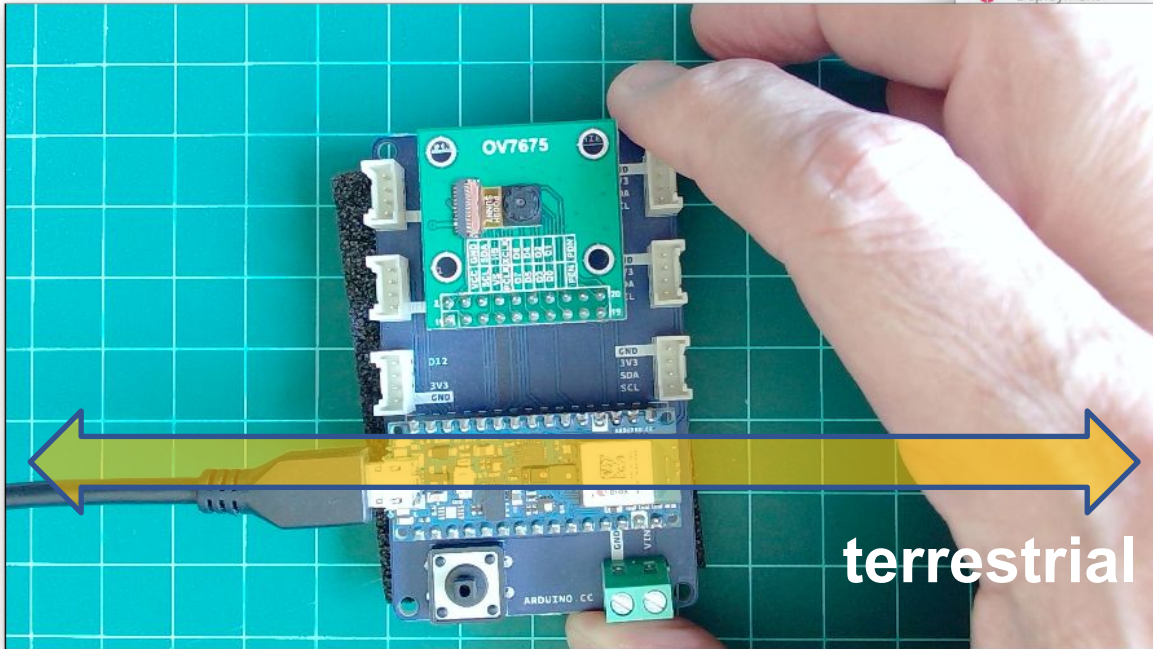
Record new data | Connect using WebUSB

Device: Nano | Label: terrestrial | Sample length (ms.): 10000 | Sensor: Sensor with 3 axes (accX, accY, accZ) | Frequency: 100Hz | Start sampling

| SAMPLE NAME             | LABEL       | ADDED           | LENGTH |
|-------------------------|-------------|-----------------|--------|
| terrestrial.json.2jv... | terrestrial | Today, 14:26:56 | 10s    |
| terrestrial.json.2jv... | terrestrial | Today, 14:26:29 | 10s    |
| terrestrial.json.2jv... | terrestrial | Today, 14:26:06 | 10s    |
| terrestrial.json.2jv... | terrestrial | Today, 14:25:48 | 10s    |
| terrestrial.json.2jv... | terrestrial | Today, 14:25:29 | 10s    |
| terrestrial.json.2jv... | terrestrial | Today, 14:25:04 | 10s    |
| terrestrial.json.2jv... | terrestrial | Today, 14:24:45 | 10s    |
| terrestrial.json.2jv... | terrestrial | Today, 14:24:21 | 10s    |
| terrestrial.json.2jv... | terrestrial | Today, 14:17:45 | 10s    |
| terrestrial.json.2jv... | terrestrial | Today, 13:01:46 | 10s    |

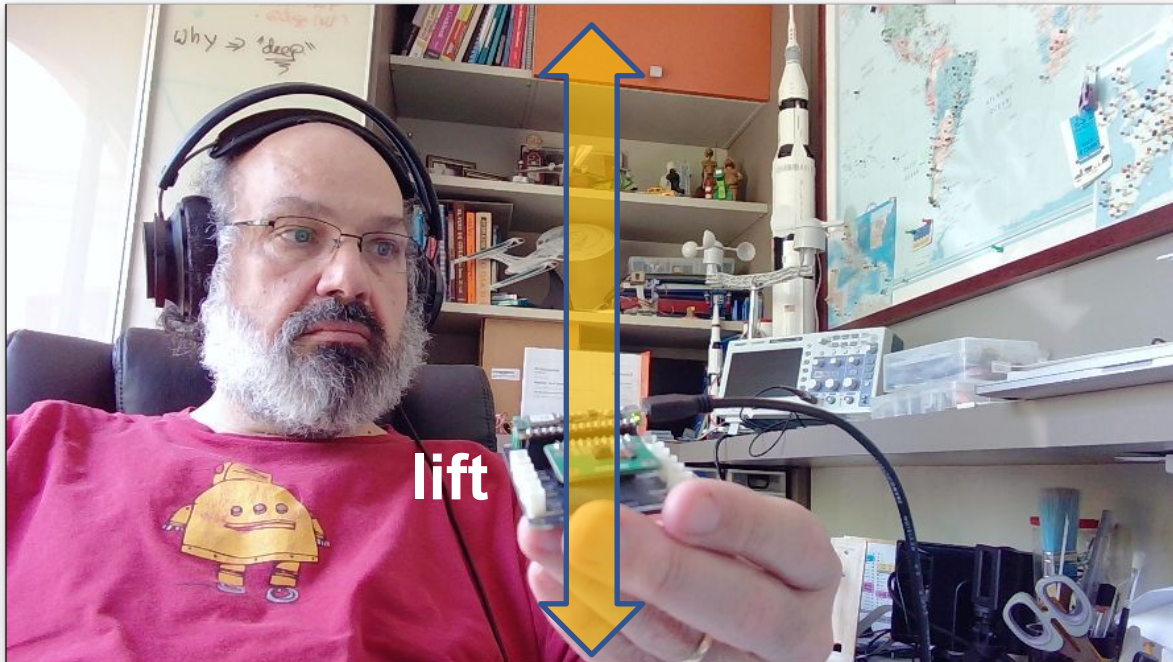
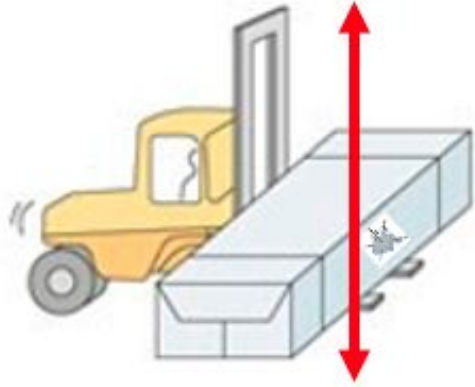
RAW DATA: terrestrial.json.2jvgelce

The raw data plot shows three acceleration axes: accX (red), accY (green), and accZ (blue) over a time period from 0 to 9360. The y-axis ranges from -20 to 20. The accX axis shows significant oscillations, while accY and accZ remain relatively flat near zero.



terrestrial

# Label: LIFT



EDGE IMPULSE

DATA ACQUISITION (IESTI01 - NANO MOTION CLASSIFICATION)

Training data | Test data

Did you know? You can capture data from any device or development board, or upload your existing datasets - Show options

DATA COLLECTED: 3m 20s

TRAIN / TEST SPLIT: 100% / 0%

Record new data: Connect using WebUSB

Device: Nano

Label: lift

Sample length (ms.): 10000

Sensor: Sensor with 3 axes (accX, accY, accZ)

Frequency: 100Hz

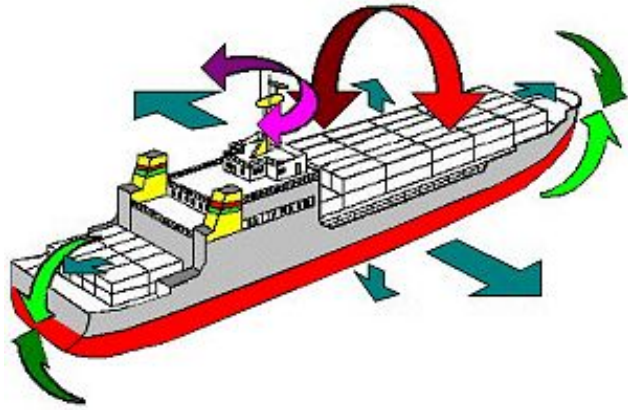
Start sampling

| SAMPLE NAME             | LABEL       | ADDED           | LENGTH |
|-------------------------|-------------|-----------------|--------|
| lift.json.2jvhabt7      | lift        | Today, 14:42:04 | 10s    |
| lift.json.2jvh9pe3      | lift        | Today, 14:41:45 | 10s    |
| lift.json.2jvh96uh      | lift        | Today, 14:41:26 | 10s    |
| lift.json.2jvh8j6q      | lift        | Today, 14:41:06 | 10s    |
| lift.json.2jvh80rg      | lift        | Today, 14:40:47 | 10s    |
| lift.json.2jvh7g2v      | lift        | Today, 14:40:30 | 10s    |
| lift.json.2jvh6uqu      | lift        | Today, 14:40:12 | 10s    |
| lift.json.2jvh6c6a      | lift        | Today, 14:39:53 | 10s    |
| lift.json.2jvh5qbe      | lift        | Today, 14:39:35 | 10s    |
| lift.json.2jvh55hs      | lift        | Today, 14:39:14 | 10s    |
| terrestrial.json.2jv... | terrestrial | Today, 14:26:56 | 10s    |
| terrestrial.json.2jv... | terrestrial | Today, 14:26:29 | 10s    |

RAW DATA: lift.json.2jvhabt7

accX accY accZ

# Label: maritime



EDGE IMPULSE

DATA ACQUISITION (IEST101 - NANO MOTION CLASSIFICATION)

Training data | Test data

Did you know? You can capture data from any device or development board, or upload your existing datasets - Show options

DATA COLLECTED: 5m 0s | TRAIN / TEST SPLIT: 100% / 0%

| SAMPLE NAME            | LABEL    | ADDED           | LENGTH |
|------------------------|----------|-----------------|--------|
| maritime.json.2jvi6... | maritime | Today, 14:57:35 | 10s    |
| maritime.json.2jvi6... | maritime | Today, 14:57:13 | 10s    |
| maritime.json.2jvi5... | maritime | Today, 14:56:48 | 10s    |
| maritime.json.2jvi4... | maritime | Today, 14:56:31 | 10s    |
| maritime.json.2jvi4... | maritime | Today, 14:56:13 | 10s    |
| maritime.json.2jvi3... | maritime | Today, 14:55:55 | 10s    |
| maritime.json.2jvi3... | maritime | Today, 14:55:36 | 10s    |
| maritime.json.2jvi2... | maritime | Today, 14:55:19 | 10s    |
| maritime.json.2jvi2... | maritime | Today, 14:55:00 | 10s    |
| maritime.json.2jvi1... | maritime | Today, 14:54:42 | 10s    |
| lift.json.2jvh9pe3     | lift     | Today, 14:42:04 | 10s    |
| lift.json.2jvh9pe3     | lift     | Today, 14:41:45 | 10s    |

Record new data | Connect using WebUSB

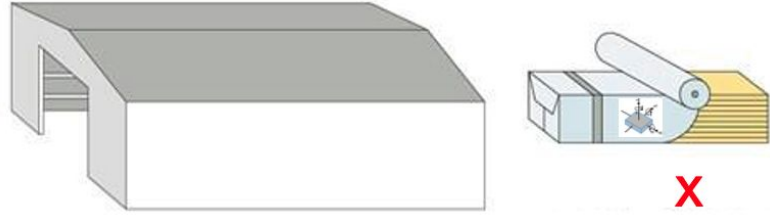
Device: Nano | Label: maritime | Sample length (ms.): 10000 | Sensor: Sensor with 3 axes (accX, accY, accZ) | Frequency: 100Hz | Start sampling

RAW DATA: maritime.json.2jvi6p3r

accX accY accZ



# Label: idle



EDGE IMPULSE

DATA ACQUISITION (IESTI01 - NANO MOTION CLASSIFICATION)

Training data | Test data

Did you know? You can capture data from any device or development board, or upload your existing datasets - Show options

DATA COLLECTED: 6m 40s

TRAIN / TEST SPLIT: 100% / 0%

Record new data [Connect using WebUSB](#)

Device: Nano

Label: idle

Sample length (ms.): 100000

Sensor: Sensor with 3 axes (accX, accY, accZ)

Frequency: 100Hz

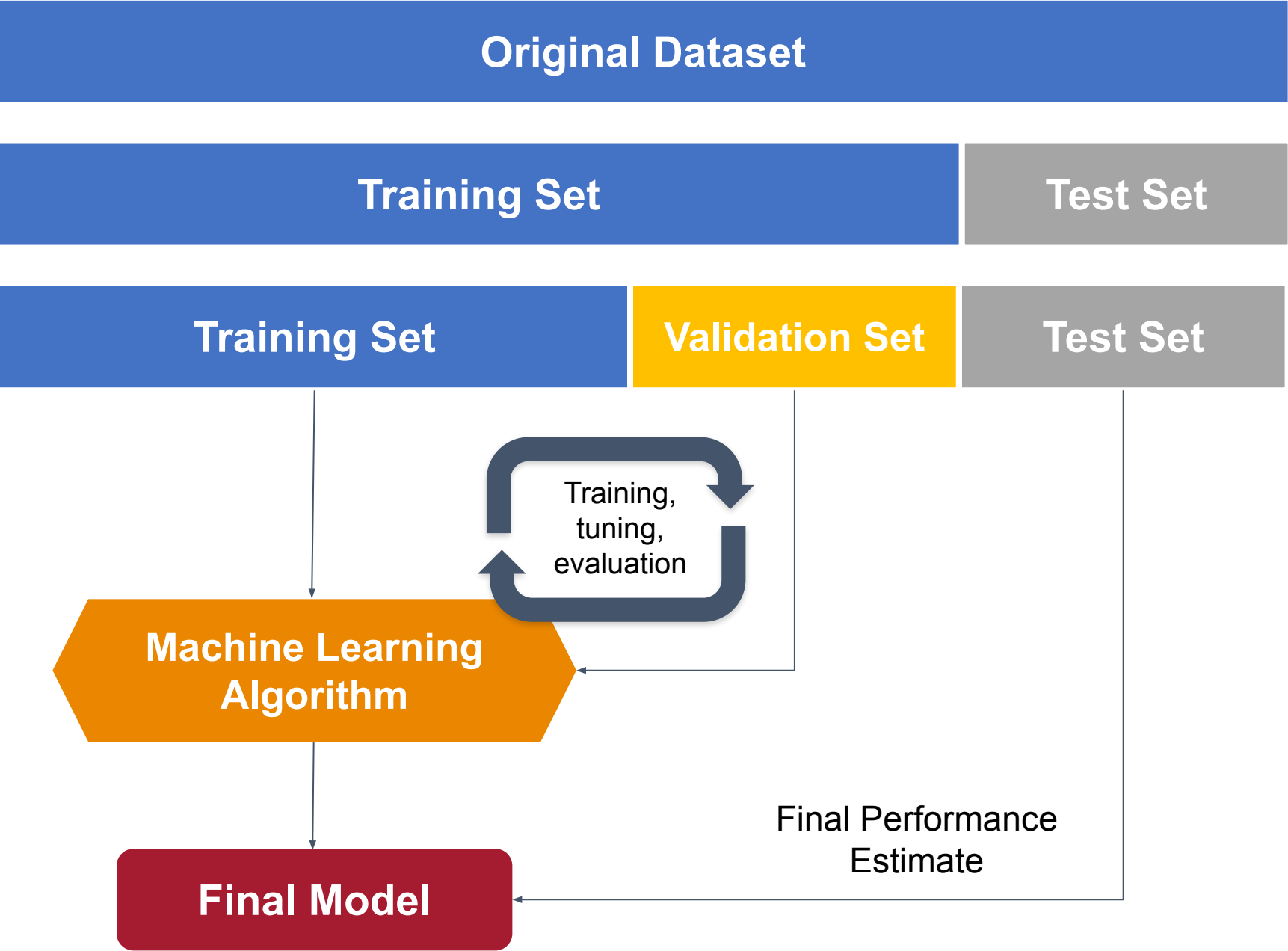
Start sampling

| SAMPLE NAME            | LABEL    | ADDED           | LENGTH |
|------------------------|----------|-----------------|--------|
| idle.json.2jvimf14     | idle     | Today, 15:06:09 | 1m 40s |
| maritime.json.2jvi6... | maritime | Today, 14:57:35 | 10s    |
| maritime.json.2jvi6... | maritime | Today, 14:57:13 | 10s    |
| maritime.json.2jvi5... | maritime | Today, 14:56:48 | 10s    |
| maritime.json.2jvi4... | maritime | Today, 14:56:31 | 10s    |
| maritime.json.2jvi4... | maritime | Today, 14:56:13 | 10s    |
| maritime.json.2jvi3... | maritime | Today, 14:55:55 | 10s    |
| maritime.json.2jvi3... | maritime | Today, 14:55:36 | 10s    |
| maritime.json.2jvi2... | maritime | Today, 14:55:19 | 10s    |
| maritime.json.2jvi2... | maritime | Today, 14:55:00 | 10s    |
| maritime.json.2jvi1... | maritime | Today, 14:54:42 | 10s    |
| lift.json.2jvhbt7      | lift     | Today, 14:42:04 | 10s    |

RAW DATA

idle.json.2jvimf14

accX accY accZ



Dashboard - IESTI01 - Nano M... x +

studio.edgeimpulse.com/studio/61345

**EDGE IMPULSE**

- Dashboard
- Devices
- Data acquisition
- Impulse design
  - Create impulse
- EON Tuner
- Retrain model
- Live classification
- Model testing
- Versioning
- Deployment

GETTING STARTED

- Documentation
- Forums

Download block output

No downloads available yet

**Performance settings**

Use GPU for training

Parallel DSP jobs

Job limit in minutes

DSP file size limit (MB)

**Administrative zone**

Show Linux deploy options ?

**Save experiments**

**Danger zone**

Perform train / test split

Delete this project

Delete all data in this project

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Dashboard - IESTI01 - Nano M... x +

studio.edgeimpulse.com/studio/61345

**EDGE IMPULSE**

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- Deployment

GETTING STARTED

- Documentation
- Forums

Download block output

No downloads available yet

**Performance settings**

Use GPU for training

Parallel DSP jobs

Job limit in minutes

DSP file size limit (MB)

**Administrative zone**

Show Linux deploy options ?

**Save experiments**

**Danger zone**

Performing split...

Delete this project

Delete all data in this project

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**Project info**

Project ID 61345

Labeling method One label per da

Latency calculations Cortex-M4F 80M

**Perform train / test split**

Are you sure you want to rebalance your dataset? This splits all your data automatically between the training and testing set, and resets the categories for all data. This is irrevocable!

Cancel **Yes, perform the train / test split**

EDGE IMPULSE

DATA ACQUISITION - TESTING (TESTING CLASSIFICATION)

Training data Test data

Did you know? You can capture data from any device or development board, or upload your existing datasets - Show options

DATA COLLECTED 40s

TRAIN / TEST SPLIT 90% / 10%

Record new data Connect using WebUSB

Device Nano

Label idle

Sample length (ms.) 100000

Sensor Sensor with 3 axes (accX, accY, accZ)

Frequency 100Hz

Start sampling

RAW DATA Click on a sample to load...

| SAMPLE NAME             | LABEL       | ADDED           | LENGTH |
|-------------------------|-------------|-----------------|--------|
| maritime.json.2jvi4...  | maritime    | Today, 14:56:13 | 10s    |
| maritime.json.2jvi1...  | maritime    | Today, 14:54:42 | 10s    |
| lift.json.2jvh6uqu      | lift        | Today, 14:40:12 | 10s    |
| terrestrial.json.2jv... | terrestrial | Today, 13:01:46 | 10s    |

Navigation: < 1 >

Left sidebar: Dashboard, Devices, Data acquisition, EON Tuner, Retrain model, Live classification, Model testing, Versioning, Deployment, GETTING STARTED, Documentation, Forums

Top right: MJRoBot (Marcelo Rovai)

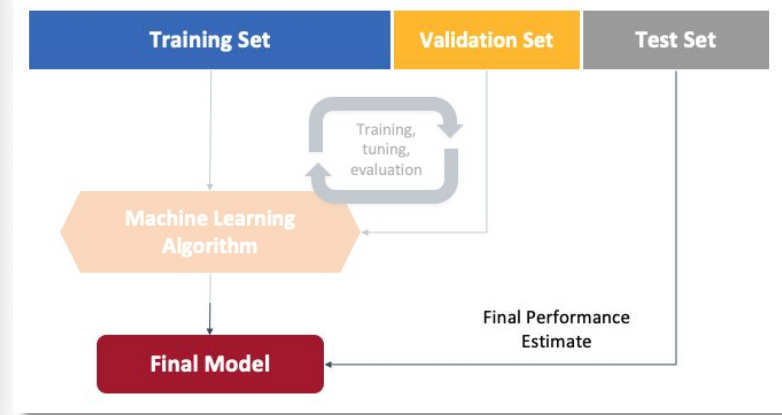
If automatic split is not good, proceed with manual split

The screenshot shows the Edge Impulse Studio interface. The top navigation bar includes the Edge Impulse logo and the user profile 'MJRoBot (Marcelo Rovai)'. The main header displays 'DATA ACQUISITION - TESTING (IE... ON CLASSIFICATION)'. Below this, there are tabs for 'Training data' and 'Test data', with an orange arrow pointing to the 'Test data' tab. A notification banner reads: 'Did you know? You can capture data from any device or development board, or upload your existing datasets - Show options'. The central dashboard features two circular progress indicators: 'DATA COLLECTED 1m 20s' and 'TRAIN / TEST SPLIT 80% / 20%'. Below these is a table of collected data:

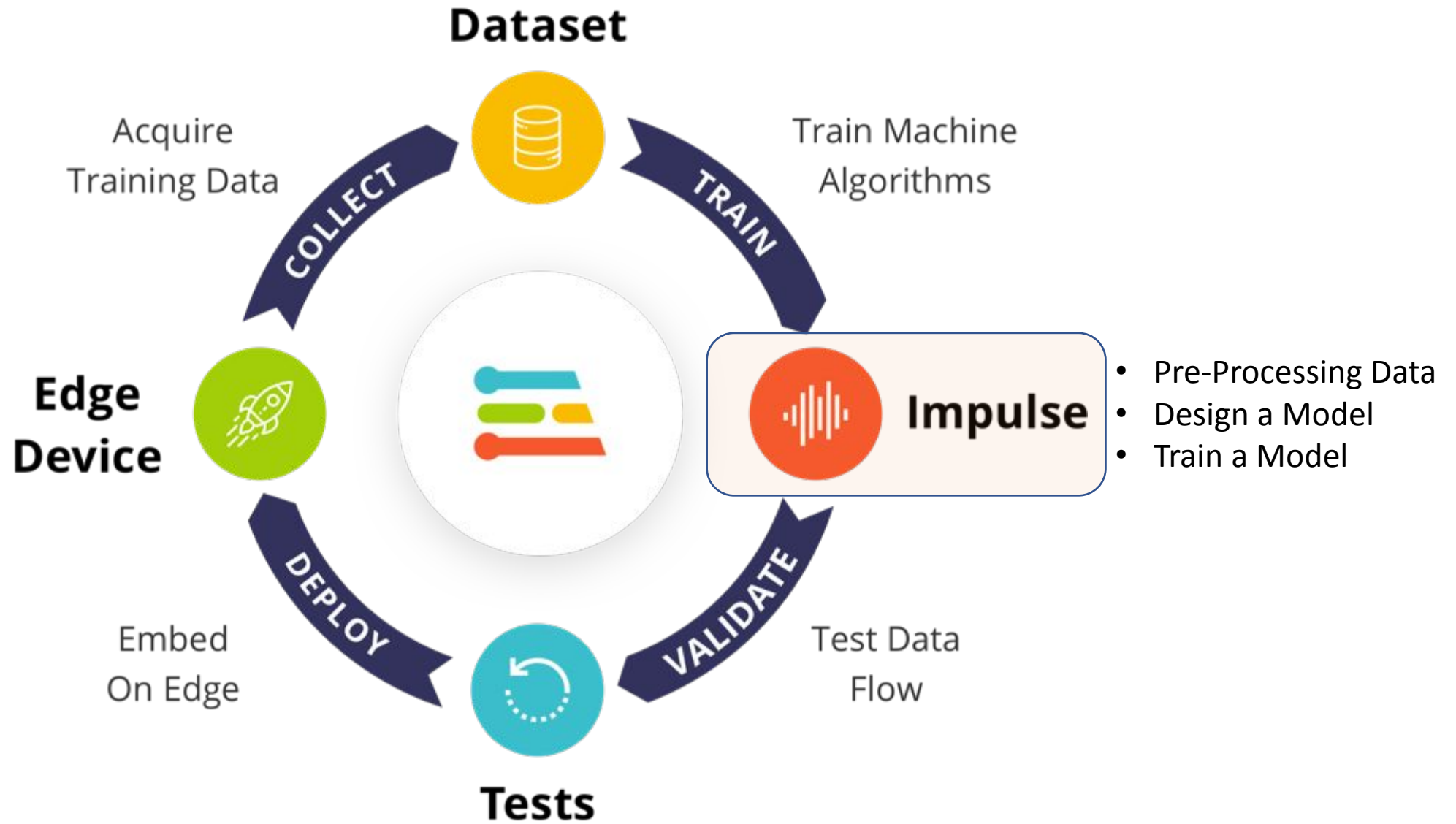
| SAMPLE NAME             | LABEL       | ADDED           | LENGTH |
|-------------------------|-------------|-----------------|--------|
| terrestrial.json.2jv... | terrestrial | Today, 15:23:49 | 10s    |
| lift.json.2jvhbt7       | lift        | Today, 15:23:38 | 10s    |
| idle.json.2jvjlvon      | idle        | Today, 15:23:22 | 20s    |
| maritime.json.2jvi4...  | maritime    | Today, 14:56:13 | 10s    |
| maritime.json.2jvi1...  | maritime    | Today, 14:54:42 | 10s    |
| lift.json.2jvh6uqu      | lift        | Today, 14:40:12 | 10s    |
| terrestrial.json.2jv... | terrestrial | Today, 13:01:46 | 10s    |

To the right of the table is a 'Record new data' section with a 'Connect using WebUSB' button. It includes fields for 'Device' (Nano), 'Label' (idle), 'Sample length (ms.)' (20000), 'Sensor' (Sensor with 3 axes (accX, accY, accZ)), and 'Frequency' (100Hz), with a 'Start sampling' button. At the bottom, a dark blue bar says 'RAW DATA Click on a sample to load...'. The left sidebar contains navigation options like 'Dashboard', 'Devices', 'Data acquisition', 'EON Tuner', 'Retrain model', 'Live classification', 'Model testing', 'Versioning', 'Deployment', 'Documentation', and 'Forums'. The 'Data acquisition' option is highlighted with an orange box.

Dataset is balanced (has representative samples from all classes) and split 80%/20%

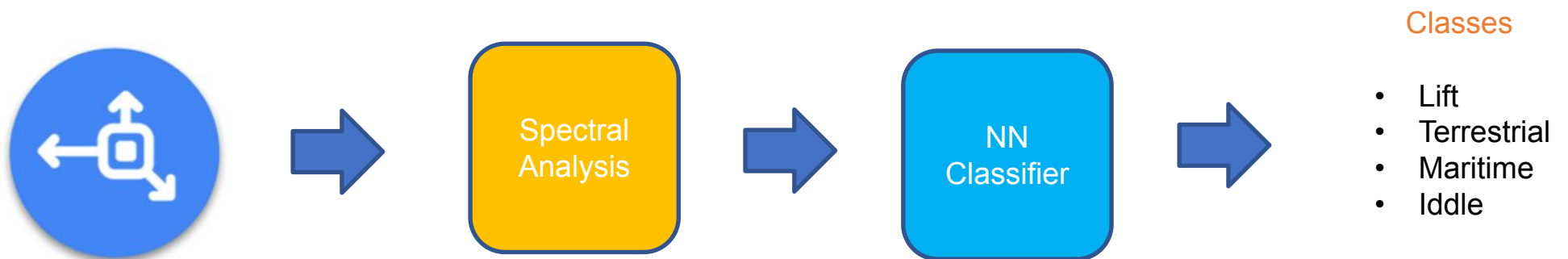






The screenshot displays a machine learning workflow interface with four main panels:

- Time series data (Red panel):** Shows axes (accX, accY, accZ), window size (2000 ms), window increase (80 ms), frequency (62.5 Hz), and zero-pad data (checked).
- Spectral Analysis (White panel):** Name: Spectral Analysis; Input axes: accX, accY, accZ.
- Neural Network (Keras) (Purple panel):** Name: Neural Network (Keras); Input features: Spectral Analysis; Output features: 4 (idle, lift, maritime, terrestrial).
- Output features (Green panel):** 4 (idle, lift, maritime, terrestrial); Save Impulse button.



Spectral features - IESTIO1 - N x +

studio.edgeimpulse.com/studio/61345/dsp/spectral-analysis/3

EDGE IMPULSE

- Dashboard
- Devices
- Data acquisition
- Impulse design
  - Create impulse
  - Spectral features**
  - NN Classifier
- EON Tuner
- Retrain model
- Live classification
- Model testing
- Versioning
- Deployment

GETTING STARTED

- Documentation
- Forums

### Raw data

terrestrial.json.2jvgdqv9 (terrestrial)

accX  
accY  
accZ

### Raw features

1.6400, -0.9700, 9.8000, 1.7100, -0.6400, 9.8100, 1.8500, -0.4200, 9.7900, 1.7800, -0.5200, 9.7500, 1.7100, ...

### Parameters

#### Scaling

Scale axes:

#### Filter

Type:  ▼

Cut-off frequency:

Order:

#### Spectral power

FFT length:

No. of peaks:

Peaks threshold:

Power edges:

[Save parameters](#)

### DSP result

#### After filter

#### Frequency domain

#### Spectral power

### Processed features

1.9614, 0.7937, 2.6663, 0.0000, 0.0000, 0.0000, 0.0000, 0.0000, 0.0000, 0.4550, 0.0489, 0.0025, 0.2078, 2.3810, 0.1...

### On-device performance

PROCESSING TIME: **9 ms.**

PEAK RAM USAGE: **5 KB**

Spectral features - IESTI01 - NANO MOTION CLASSIFICATION

studio.edgeimpulse.com/studio/61345/dsp/spectral-analysis/3/generate-features

MJRoBot (Marcelo Roval)

**EDGE IMPULSE**

SPECTRAL FEATURES (IESTI01 - NANO MOTION CLASSIFICATION)

#1 Click to set a description for this version

Parameters **Generate features**

### Training set

|                      |                                       |
|----------------------|---------------------------------------|
| Data in training set | 5m 20s                                |
| Classes              | 4 (idle, lift, maritime, terrestrial) |
| Window length        | 2000 ms.                              |
| Window increase      | 80 ms.                                |
| Training windows     | 3,400                                 |

**Generate features**

### Feature generation output

```

Job started
Creating windows from 25 files...
[ 0/25] Creating windows from files...
[ 1/25] Creating windows from files...
[25/25] Creating windows from files...
Created 3400 windows: idle: 976, lift: 808, maritime: 808, terrestrial: 808

Creating features
[ 1/3400] Creating features...
[ 898/3400] Creating features...
[1798/3400] Creating features...
[2704/3400] Creating features...
[3400/3400] Creating features...
Created features

Job completed

```

### Feature explorer (3,400 samples)

X Axis: accX RMS | Y Axis: accY RMS | Z Axis: accZ RMS

- idle
- lift
- maritime
- terrestrial

**maritime.json.2jvi4q7**  
Window: 240 - 2240 ms.  
Label: maritime  
[View sample](#)  
[View features](#)

### On-device performance

**PROCESSING TIME**  
9 ms.

**PEAK RAM USAGE**  
5 KB

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## Neural Network settings

### Training settings

Number of training cycles ⓘ

Learning rate ⓘ

### Neural network architecture

Input layer (33 features)

Dense layer (20 neurons)

Dense layer (10 neurons)

Add an extra layer

Output layer (4 classes)

Start training

## Model

Model version: ⓘ Quantized (int8) ▾

Last training performance (validation set)

**ACCURACY**  
99.9%

**LOSS**  
0.01

Confusion matrix (validation set)

|             | IDLE | LIFT  | MARITIME | TERRESTRIAL |
|-------------|------|-------|----------|-------------|
| IDLE        | 100% | 0%    | 0%       | 0%          |
| LIFT        | 0%   | 99.4% | 0.6%     | 0%          |
| MARITIME    | 0%   | 0%    | 100%     | 0%          |
| TERRESTRIAL | 0%   | 0%    | 0%       | 100%        |
| F1 SCORE    | 1.00 | 1.00  | 1.00     | 1.00        |

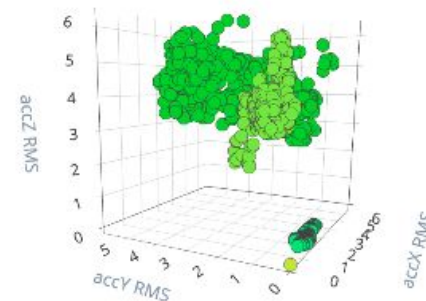
Feature explorer (full training set) ⓘ

accX RMS ▾

accY RMS ▾

accZ RMS ▾

- idle - correct
- lift - correct
- maritime - correct
- terrestrial - correct
- lift - incorrect

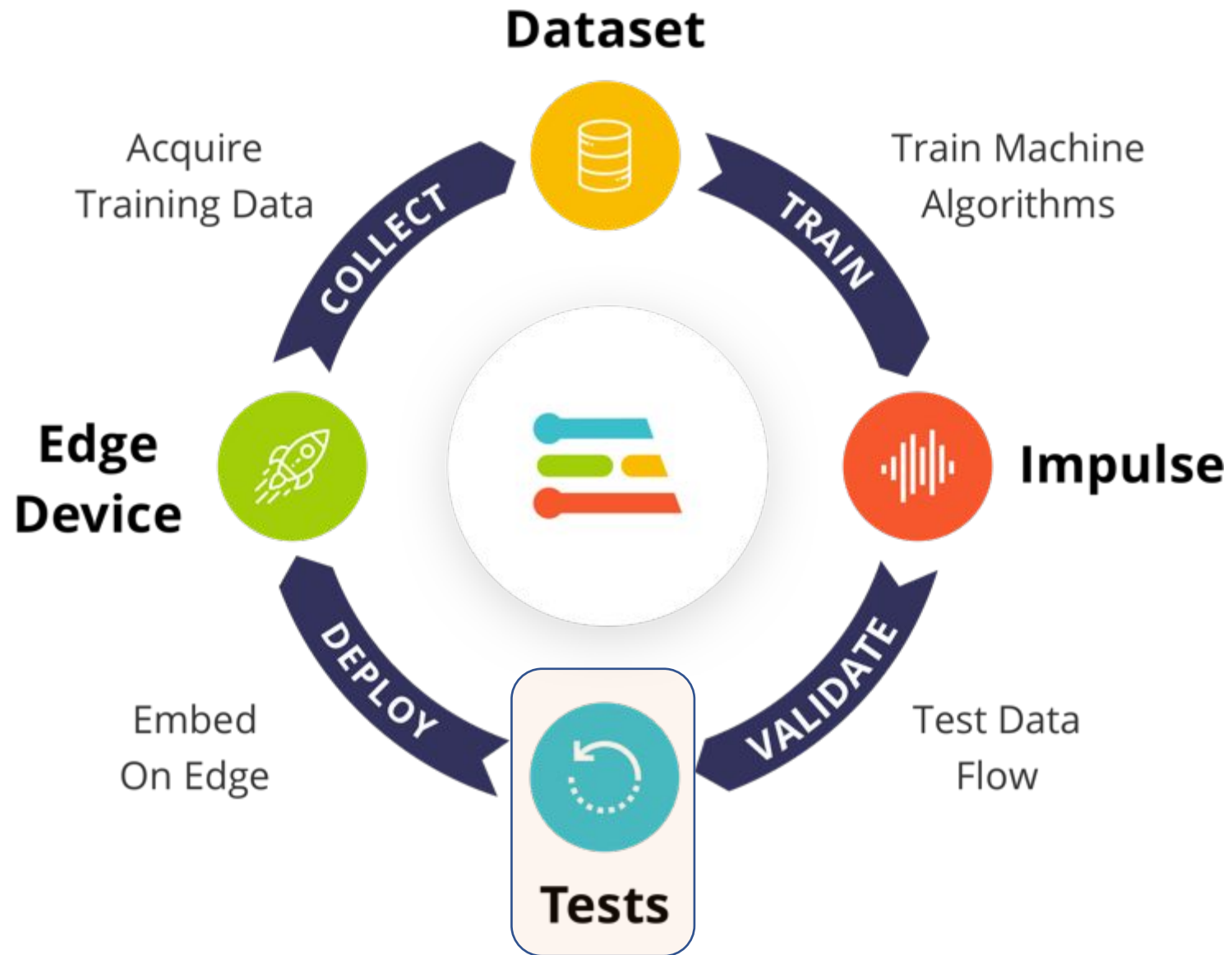


On-device performance ⓘ

**INFERRING TIME**  
1 ms.

**PEAK RAM USAGE**  
1.7K

**FLASH USAGE**  
19.0K



Model testing - IESTI01 - Nano x

studio.edgeimpulse.com/studio/61345/validation

**EDGE IMPULSE**

- Dashboard
- Devices
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  - Spectral features
  - NN Classifier
- EON Tuner
- Retrain model
- Live classification
- Model testing**
- Versioning
- Deployment

GETTING STARTED

- Documentation
- Forums

### Test data

Classify all

Set the 'expected outcome' for each sample to the desired outcome to automatically score the impulse.

| SAMPLE NAME           | EXPECTED OUTCOME | LENGTH | ACCURACY | RESULT          |
|-----------------------|------------------|--------|----------|-----------------|
| terrestrial.json.2... | terrestrial      | 10s    | 100%     | 101 terrestrial |
| lift.json.2jvhabt7    | lift             | 10s    | 100%     | 101 lift        |
| idle.json.2jvjlvon    | idle             | 20s    | 100%     | 226 idle        |
| maritime.json.2j...   | maritime         | 10s    | 100%     | 101 maritime    |
| maritime.json.2j...   | maritime         | 10s    | 100%     | 101 maritime    |
| lift.json.2jvh6uqu    | lift             | 10s    | 100%     | 101 lift        |
| terrestrial.json.2... | terrestrial      | 10s    | 100%     | 101 terrestrial |

### Model testing output

```

Classifying data for MN Classifier...
Copying features from processing blocks...
Copying features from DSP block...
Copying features from DSP block OK
Copying features from processing blocks OK

Classifying data for float32 model...
Scheduling job in cluster...
Job started
Classifying data for MN Classifier OK
    
```

Job completed

### Model testing results

ACCURACY 100.00%

|             | IDLE | LIFT | MARITIME | TERRESTRIAL | UNCERTAIN |
|-------------|------|------|----------|-------------|-----------|
| IDLE        | 100% | 0%   | 0%       | 0%          | 0%        |
| LIFT        | 0%   | 100% | 0%       | 0%          | 0%        |
| MARITIME    | 0%   | 0%   | 100%     | 0%          | 0%        |
| TERRESTRIAL | 0%   | 0%   | 0%       | 100%        | 0%        |
| F1 SCORE    | 1.00 | 1.00 | 1.00     | 1.00        |           |

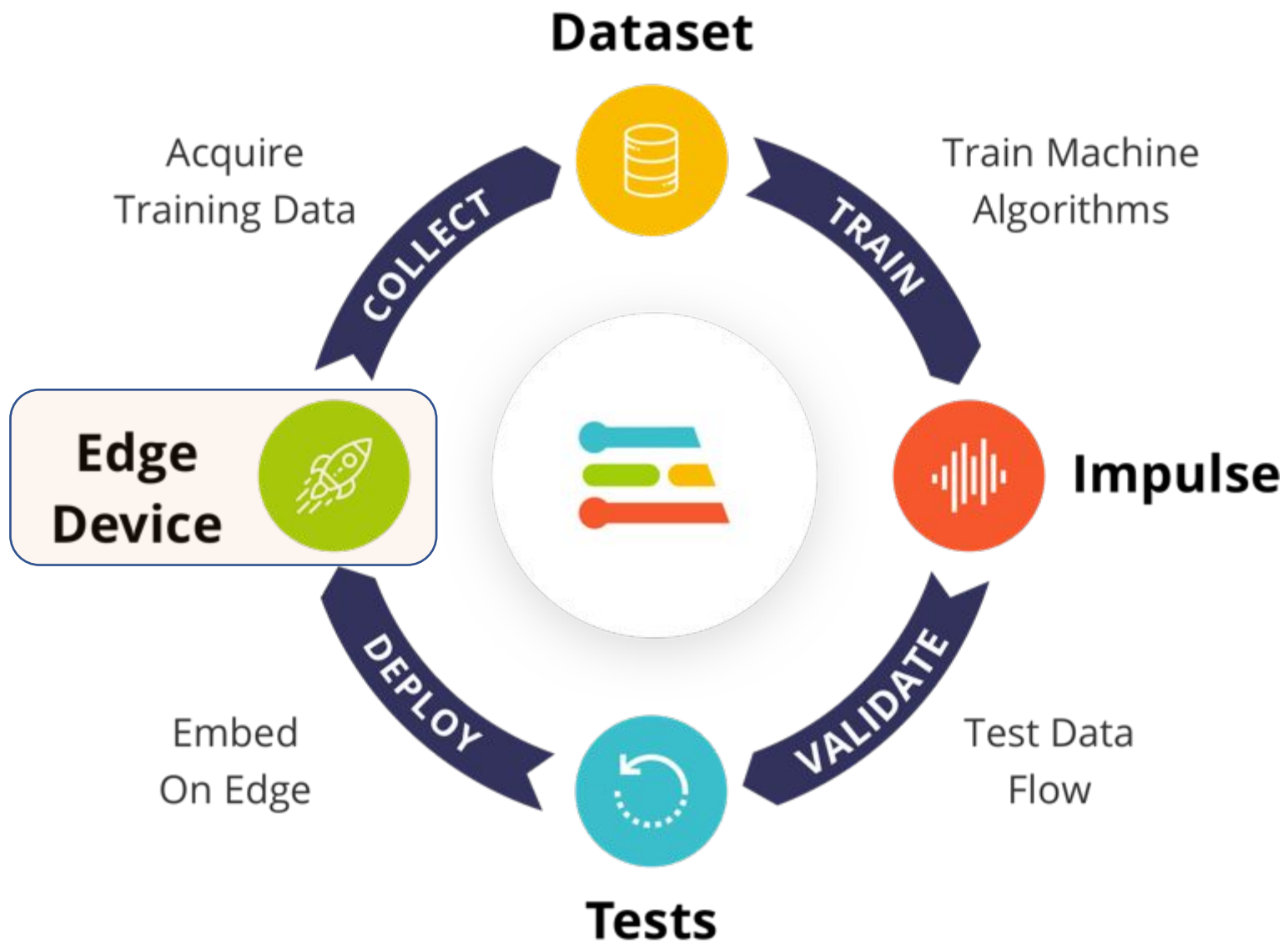
```

graph TD
    TS[Training Set] --> ML[Machine Learning Algorithm]
    VS[Validation Set] --> ML
    ML --> FE[Final Performance Estimate]
    ML --> FM[Final Model]
    FE --> ML
    TS --> FE
    VS --> FE
    
```

### Feature explorer

accX RMS | accY RMS | accZ RMS

- idle - correct
- lift - correct
- maritime - correct
- terrestrial - correct



- Pre-Processing Data
- Design a Model
- Train a Model



Deployment - IEST101 - Nano x

studio.edgeimpulse.com/studio/61345/deployment

MJRoBot (Marcelo Rovai)

### EDGE IMPULSE






DEPLOYMENT (IEST101 - NANO MOTION CLASSIFICATION)

#### Deploy your impulse

You can deploy your impulse to any device. This makes the model run without an internet connection, minimizes latency, and runs with minimal power consumption. [Read more.](#)










#### Create library

Turn your impulse into optimized source code that you can run on any device.

|  |   |   |
|--|---|---|
| <br>C++ library | <br>Arduino library  | <br>Cube.MX CMSIS-PACK |
| <br>WebAssembly | <br>TensorRT library |   |

#### Build firmware

Or get a ready-to-go binary for your development board that includes your impulse.

|  |   |   |
|--|---|---|
| <br>ST IoT Discovery Kit          | <br>Arduino Nano 33 BLE Sense    | <br>Eta Compute ECM3532 AI Sensor <span>END OF LIFE</span> |
| <br>SiLabs Thunderboard Sense 2  | <br>Himax WE-I Plus             | <br>Nordic nRF52840 DK + IKS02A1                          |
| <br>Nordic nRF5340 DK + IKS02A1 | <br>Nordic nRF9160 DK + IKS02A1 | <br>Nordic Thingy:91                                     |

#### Build output

```
Creating job... OK (ID: 1646786)
Writing templates...
Writing templates OK
Copying Edge Impulse SDK...
Copying Edge Impulse SDK OK
Compiling EON model...
Compiling EON model OK
Removing clutter and updating headers...
Removing clutter and updating headers OK
Creating archive...
Job started
Creating archive OK
Job completed
```

ei-iest101---nano....zip

Show All

Deployment - IESTI01 - Nano x +

studio.edgeimpulse.com/studio/61345/deployment

**EDGE IMPULSE**

- Dashboard
- Devices
- Data acquisition
- Impulse design
  - Create impulse
  - Spectral features
  - NN Classifier
- EON Tuner
- Retrain model
- Live classification
- Model testing
- Versioning
- Deployment

GETTING STARTED

- Documentation
- Forums

SilLabs Thunderboard Sense 2

Himax WE-I Plus

Nordic nRF52840 DK + IKS02A1

Nordic nRF5340 DK + IKS02A1

Nordic nRF9160 DK + IKS02A1

Nordic Thingy:91

Sony's Spresense

**Select optimizations (optional)**

Model optimizations can increase on-de device performance. Choose from the recommended choices for your target. Click on a choice to learn more.

**Enable EON™ Compiler**  
Same accuracy, up to 50% less RAM usage

**Available optimizations for NN Classifier**

| Optimization  | RAM USAGE | LATENCY | ACCURACY |
|---|-----------|---------|----------|
| <b>Quantized (int8)</b> ★<br><a href="#">Currently selected</a> | 19.0K     | 100%    | 100%     |
| <b>Unoptimized (float32)</b><br><a href="#">Click to select</a> | 1.8K      | 1 ms    | 100%     |

FLASH USAGE  
21.3K

CONFUSION MATRIX

|     |     |     |     |   |
|-----|-----|-----|-----|---|
| 100 | 0   | 0   | 0   | 0 |
| 0   | 100 | 0   | 0   | 0 |
| 0   | 0   | 100 | 0   | 0 |
| 0   | 0   | 0   | 100 | 0 |

Estimate for Cortex-M4F 80MHz

**Build**

**Build output**

```
Creating job... OK (ID: 1646786)
Writing templates...
Writing templates OK
Copying Edge Impulse SDK...
Copying Edge Impulse SDK OK
Compiling EON model...
Compiling EON model OK
Removing clutter and updating headers...
Removing clutter and updating headers OK
Creating archive...
Archive OK
```

**Built Arduino library**

Add this library through the Arduino IDE via:  
**Sketch > Include Library > Add .ZIP Library...**

Examples can then be found under:  
**File > Examples > IESTI01\_Nano\_Motion\_Classification\_inferencing**

ei-iesti01---nano....zip ^

Show All x

- Verify/Compile ⌘R
- Upload ⌘U
- Upload Using Programmer ⇧⌘U
- Export compiled Binary ⌘S
- Show Sketch Folder ⌘K
- Include Library**
- Add File...

Manage Libraries... ⌘I

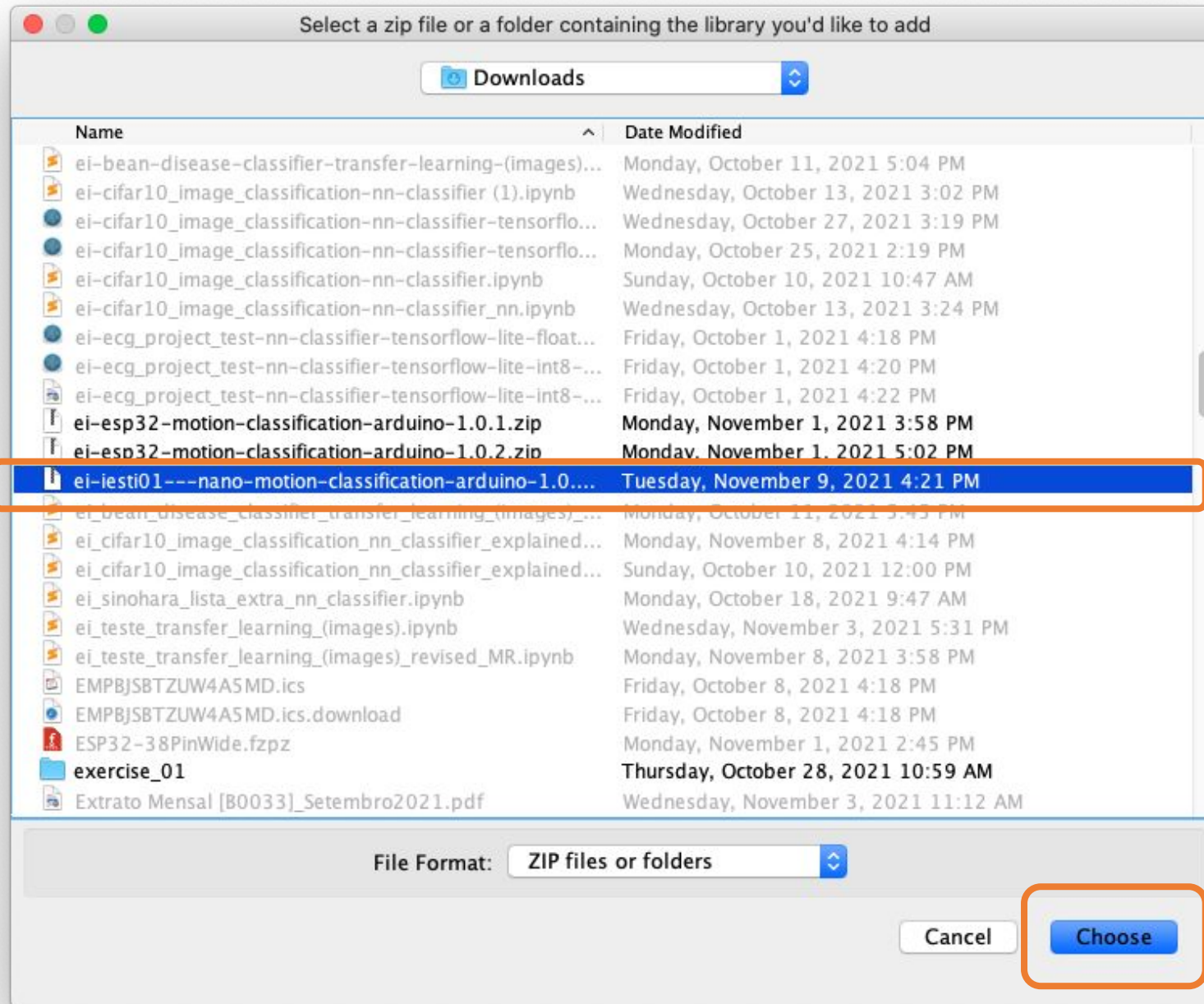
Add .ZIP Library...

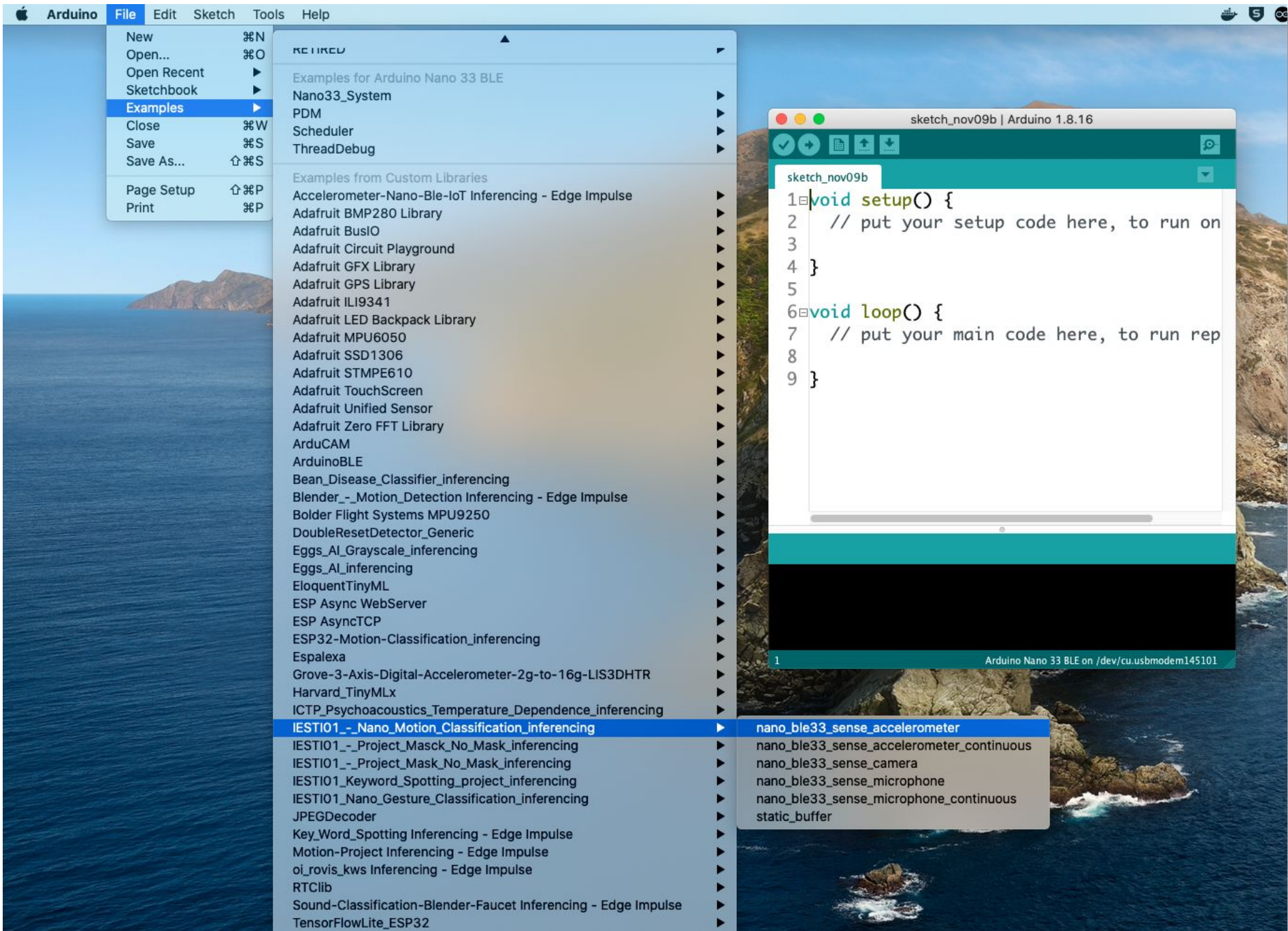
- Arduino libraries
- Arduino Low Power
  - ArduinoBLE
  - Arduino\_APDS9960
  - Arduino\_CRC32
  - Arduino\_HTS221
  - Arduino\_LPS22HB
  - Arduino\_LSM6DS3
  - Arduino\_LSM9DS1
  - Arduino\_OV767X
  - Arduino\_TensorFlowLite
  - Bridge
  - Esplora
  - Ethernet
  - Firmata
  - GSM
  - Keyboard
  - LiquidCrystal
  - MRI - Monitor for Remote Inspection
  - Madgwick
  - Mouse
  - Nano33\_System
  - PDM
  - RTCZero
  - Robot Control
  - Robot IR Remote
  - Robot Motor
  - SD
  - SFU
  - SPI
  - Scheduler
  - Servo
  - SpacebrewYun
  - Stepper
  - TFT
  - Temboo
  - ThreadDebug
  - USBHID
  - USBMSD
  - WiFi
  - WiFinINA
  - Wire

```

sketch_jun28a
1 void setup() {
2   // put your setup code here, to run on
3
4 }
5
6 void loop() {
7   // put your main code here, to run rep
8
9 }

```

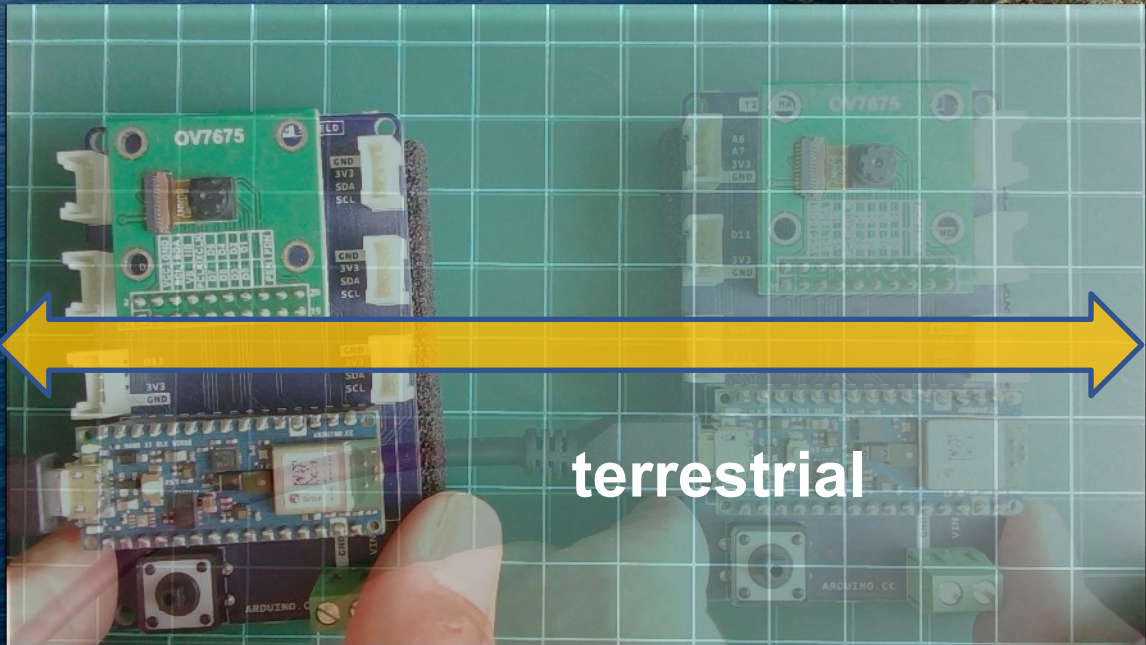




# Model Inference

```
Arduino File Edit Sketch Tools Help
/dev/cu.usbmodem145101
Send
Sampling...
Predictions (DSP: 20 ms., Classification: 0 ms., Anomaly: 0 ms.):
  idle: 0.00000
  lift: 0.00000
  maritime: 0.00000
  terrestrial: 0.99609
Starting inferencing in 2 seconds...
Sampling...
Predictions (DSP: 20 ms., Classification: 1 ms., Anomaly: 0 ms.):
  idle: 0.00000
  lift: 0.00000
  maritime: 0.00000
  terrestrial: 0.99609
Starting inferencing in 2 seconds...
 Autoscroll  Show timestamp
Both NL & CR 115200 baud Clear output
```

```
nano_ble33_sense_accelerometer | Arduino 1.8.16
nano_ble33_sense_accelerometer
1 /* Edge Impulse Arduino examples
2  * Copyright (c) 2021 EdgeImpulse Inc.
3  *
4  * Permission is hereby granted, free of charge, to any person obtaining a copy
5  * of this software and associated documentation files (the "Software"), to use,
6  * in the Software without restriction, including without limitation the rights
7  * to use, copy, modify, merge, publish, distribute, sublicense, and/or sell
8  * copies of the Software, and to permit persons to whom the Software is
9  * furnished to do so, subject to the following conditions:
10 *
11 * The above copyright notice and this permission notice shall be included in
12 * all copies or substantial portions of the Software.
13 *
14 * THE SOFTWARE IS PROVIDED "AS IS", WITHOUT WARRANTY OF ANY KIND, EXPRESS OR
15 * IMPLIED, INCLUDING BUT NOT LIMITED TO THE WARRANTIES OF MERCHANTABILITY,
16 * FITNESS FOR A PARTICULAR PURPOSE AND NONINFRINGEMENT. IN NO EVENT SHALL THE
17 * AUTHORS OR COPYRIGHT HOLDERS BE LIABLE FOR ANY CLAIM, DAMAGES OR OTHER
18 * LIABILITY, WHETHER IN AN ACTION OF CONTRACT, TORT OR OTHERWISE, ARISING FROM
19 * OUT OF OR IN CONNECTION WITH THE SOFTWARE OR THE USE OR OTHER DEALINGS IN
20 * THE SOFTWARE.
21 */
22
23 /* Includes -----
24 #include <IESTI01_-_Nano_Motion_Classification_inferencing.h>
25 #include <Arduino_LSM9DS1.h>
26
27 /* Constant defines -----
28 #define CONVERT_G_TO_MS2 9.80665f
29
30 /* Private variables -----
31 static bool debug_nn = false; // Set this to true to see e.g. features generated
32
Done in 6.027 seconds
reset()
```



terrestrial

```

/dev/cu.usbmodem145101
Send

Predictions (DSP: 29 ms., Classification: 0 ms., Anomaly: 0 ms.): terrestrial [ 0, 0, 0, 10, 0, 0,
Predictions (DSP: 29 ms., Classification: 0 ms., Anomaly: 0 ms.): terrestrial [ 0, 0, 0, 10, 0, 0,
Predictions (DSP: 29 ms., Classification: 0 ms., Anomaly: 0 ms.): terrestrial [ 0, 0, 0, 10, 0, 0,
Predictions (DSP: 29 ms., Classification: 0 ms., Anomaly: 0 ms.): terrestrial [ 0, 0, 0, 10, 0, 0,
Predictions (DSP: 29 ms., Classification: 0 ms., Anomaly: 0 ms.): terrestrial [ 0, 0, 0, 10, 0, 0,
Predictions (DSP: 29 ms., Classification: 0 ms., Anomaly: 0 ms.): terrestrial [ 0, 0, 0, 10, 0, 0,
Predictions (DSP: 29 ms., Classification: 0 ms., Anomaly: 0 ms.): terrestrial [ 0, 0, 0, 10, 0, 0,
Predictions (DSP: 29 ms., Classification: 0 ms., Anomaly: 0 ms.): terrestrial [ 0, 0, 0, 10, 0, 0,
Predictions (DSP: 27 ms., Classification: 0 ms., Anomaly: 0 ms.): terrestrial [ 0, 0, 0, 10, 0, 0,
Predictions (DSP: 27 ms., Classification: 0 ms., Anomaly: 0 ms.): terrestrial [ 0, 0, 0, 10, 0, 0,
Predictions (DSP: 27 ms., Classification: 0 ms., Anomaly: 0 ms.): terrestrial [ 0, 0, 0, 10, 0, 0,
Predictions (DSP: 27 ms., Classification: 0 ms., Anomaly: 0 ms.): terrestrial [ 0, 0, 0, 10, 0, 0,
Predictions (DSP: 29 ms., Classification: 0 ms., Anomaly: 0 ms.): terrestrial [ 0, 0, 0, 10, 0, 0,
Predictions (DSP: 29 ms., Classification: 0 ms., Anomaly: 0 ms.): terrestrial [ 0, 0, 0, 10, 0, 0,

```

Autoscroll    Show timestamp   Both NL & CR   115200 baud   Clear output



```

nano_ble33_sense_accelerometer_continuous | Arduino 1.8.16
nano_ble33_sense_accelerometer_continuous
22
23 /* Includes -----
24 #include <IESTI01_-_Nano_Motion_Classification_inferencing.h>
25 #include <Arduino_LSM9DS1.h>
26
27 /* Constant defines -----
28 #define CONVERT_G_TO_MS2    9.80665f
29
30 /* Private variables -----
31 static bool debug_nn = false; // Set this to true to see e.g. features
32 static uint32_t run_inference_every_ms = 200;
33 static rtos::Thread inference_thread(osPriorityLow);
34 static float buffer[EI_CLASSIFIER_DSP_INPUT_FRAME_SIZE] = { 0 };
35 static float inference_buffer[EI_CLASSIFIER_DSP_INPUT_FRAME_SIZE];
36
37 /* Forward declaration */
38 void run_inference_background();
39
40 /**
41 * @brief    Arduino setup function
42 */
43 void setup()
44 {
45     // put your setup code here, to run once:
46     Serial.begin(115200);
47     Serial.println("Edge Impulse Inferencing Demo");
48
49     if (!IMU.begin()) {
50         ei_printf("Failed to initialize IMU!\r\n");
51     }
52     else {
53         ei_printf("IMU initialized\r\n");
54     }
55 }

```

Done uploading.

Done in 6.034 seconds  
reset()

40 Arduino Nano 33 BLE on /dev/cu.usbmodem145101



TinyML motion classification uses  
on **Real Life**

# Cow Monitoring

## Using the Internet of Things for Agricultural Monitoring

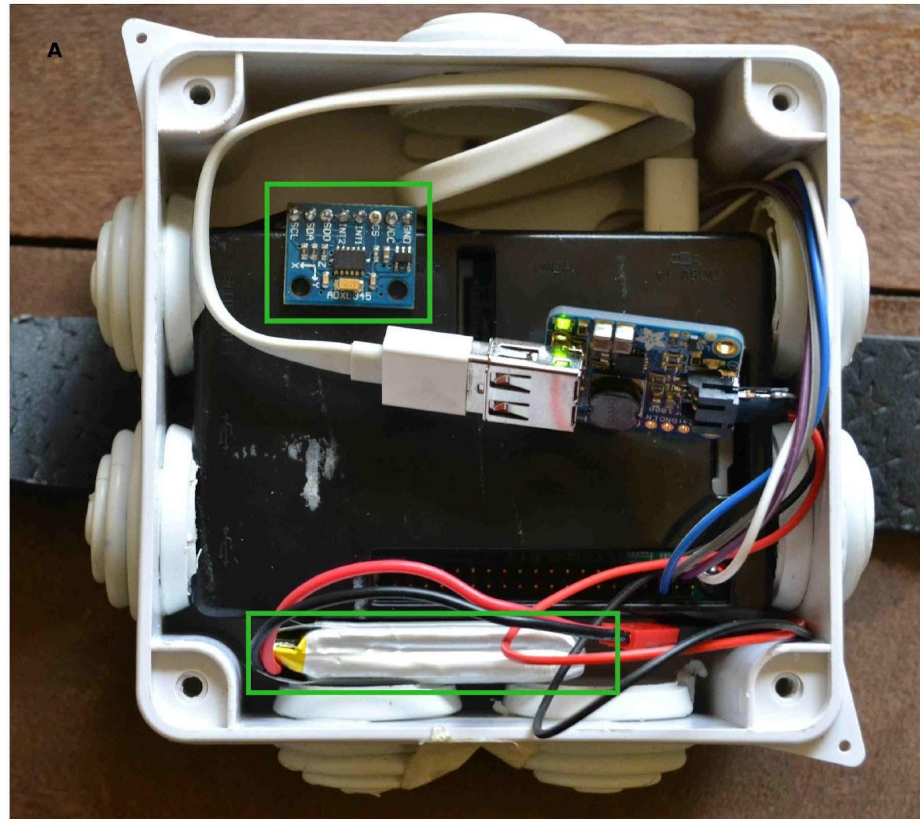
“We aim to deploy a variety of sensors for agricultural monitoring. One of the projects involves using **accelerometer sensors** to monitor activity levels in dairy cows with a view to determining when the cows are on heat or when they are sick.”



Ciira wa Maina, Ph.D.

Senior Lecturer  
Department of Electrical and Electronic Engineering  
Dedan Kimathi University of Technology  
Nyeri Kenya  
Email: ciira.maina@dkut.ac.ke

Kenia



<https://sites.google.com/site/cwamainadekut/research>

# Predict and classify common Elephant behavior



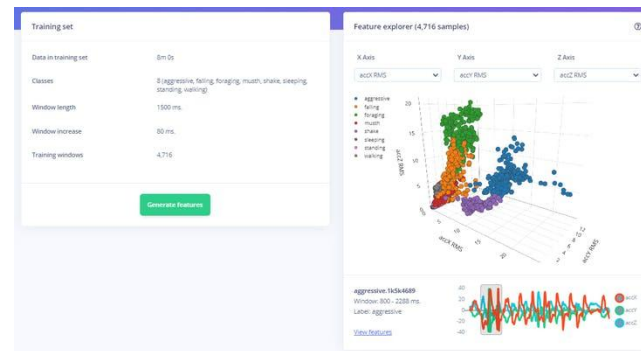
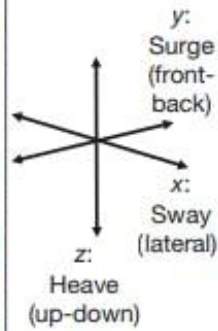
Aggressive



Standing



Sleeping



[https://www.hackster.io/dhruvsheth\\_/eletect-tinyml-and-iot-based-smart-wildlife-tracker-c03e5a#toc-accelerometer-data-models-4](https://www.hackster.io/dhruvsheth_/eletect-tinyml-and-iot-based-smart-wildlife-tracker-c03e5a#toc-accelerometer-data-models-4)

# Thanks

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